# Interaction graph, modules and large scale networks

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# Modules?

## A module exists by the question it is associated to

A module is a set of molecules and interactions that satisfy a specific property

## **Biological criteria**

- Biological modules : nodes belongs to the same biological process
- Spacial modules : elements share the same cellular localization
- Time-scale modules : nodes have the same time-scale dynamics

## Dynamical criteria

- Time-scale modules : nodes have the same time-scale dynamics
- In-out systems : Their exists a monotonicity relation in the variable behavior (monotonic systems)
- Circuit analysis : Loops that have an influence on the bistability or homeostasie of the system
- Path analysis : Decomposition into minimal paths (Flux Balance Analysis)

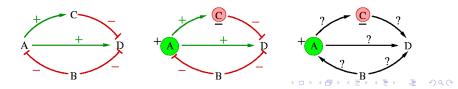
# Several methods from *dynamical systems* that can be applied to networks with a few hundreds nodes

Static analysis and modules

Main object of the talk

An analysis of shift equilibria allows to identify meaninful modules in large scale networks

- Used data and models
  - Interaction graph :  $A \rightarrow B$  if A induces a change in the production of B.
    - Signed... : signed interactions are obtained by the reading of the litterature
    - Or unsigned interactions : Chip-Chip experimentations or inference process provide unsigned interactions
  - Qualitative variation datasets between two stationnary states : DNA Chip, experimental stress or mutant



# Questions...

## Asked by biologists

- Consistency between knowledge and data
- Corrections of the model ?
- Prediction of new information
  - Variation for nonobserved products
  - Proposition for the signs of interaction when unknown
- Key nodes
  - For the validation of the model
  - For the understanding of behaviors
  - For the analysis of supplementary material (eQTL)

## The main idea

To each question we can associate a type of module that can be computed quite efficiently

# Method : Setting constraints depending on the type of avalaible data

## Variables

 signs of the variation of products ΔX(i, η) in each considered experimentation

(underlying hypothesis : data concern stationnary state shifts)

## ▶ signs of interactions $s(i \rightarrow k)$

(underlying restrictive hypothesis : every actor has a constant action on its target)

## Constraints

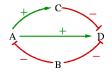
- litterature knowledge set up the signs of some interactions
- qualitative data set up the sign of some variations
- General constraint : the variation of an *internal* product is explained by the variation of one of its predecessors

 $sign(\Delta X(i,\eta)) \simeq \sum_{k \neq i, k \to i} sign(s(i \to k)) \times sign(\Delta X(k,\eta)).$ 

# Example 1 : interaction signs are known

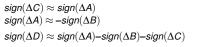
$$sign(\Delta X(i,\eta)) \simeq \sum_{k \neq i,k \to i} sign(s(i \to k)) \times sign(\Delta X(k,\eta)).$$

Usual sign rules and additional rules : ++-=?  $+ \neq -$ 



- The variation of C is given by the variation of A sign(ΔC) ≈ sign(ΔA)
- the variation of A is the opposite of the variation of B sign(ΔA) ≈ -sign(ΔB)
- the variation of D must be equal to the variation of A, -B or -C.

 $sign(\Delta D) \approx sign(\Delta A) - sign(\Delta B) - sign(\Delta C)$ 



A possible solution to the system :

≈ +

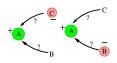
 $\begin{array}{l} \bullet \quad \approx \quad -(-) \\ \bullet \quad \approx \quad \bullet - (-) - (\bullet) \end{array}$ 

There are 4 sets of solutions (among 16 possible)



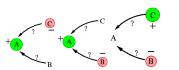
# Example 2 : interaction signs are not known





$$\begin{split} & sign(\Delta A) \simeq sign(C \to A) sign(\Delta C) \\ & sign(\Delta A) = \texttt{+} \\ & sign(\Delta C) = \texttt{-} \end{split}$$

$$\begin{split} & sign(\Delta A^{(1)}) \simeq sign(C \to A) sign(\Delta C^{(1)}) \\ & sign(\Delta A^{(2)}) \simeq sign(B \to A) sign(\Delta B^{(2)}) \\ & sign(\Delta A^{(1)}) = + \\ & sign(\Delta C^{(1)}) = - \\ & sign(\Delta A^{(2)}) = + \\ & sign(\Delta B^{(2)}) = - \end{split}$$



$$\begin{split} & sign(\Delta A^{(1)}) \simeq sign(C \to A) sign(\Delta C^{(1)}) \\ & sign(\Delta A^{(2)}) \simeq sign(B \to A) sign(\Delta B^{(2)}) \\ & sign(\Delta A^{(3)}) \simeq sign(C \to A) sign(\Delta C^{(3)}) \\ & sign(\Delta A^{(3)}) \simeq sign(B \to A) sign(\Delta B^{(3)}) \\ & sign(\Delta A^{(1)}) = + \\ & sign(\Delta C^{(1)}) = - \\ & sign(\Delta A^{(2)}) = + \\ & sign(\Delta B^{(2)}) = - \\ & sign(\Delta B^{(3)}) = + \\ & sign(\Delta C^{(3)}) = - \end{split}$$

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# Studying constraints

## Biological questions raise technical duties on systems

- Solving systems
- Eliminating variables
- Reducing systems
- Isolating subsystems

## Two mains tools to realize these tasks

- Enumeration of solutions by Decision Diagrams (Pyquali)
  - ► Compact representation of the solutions in {+,-}
  - Elimination of variables
  - Efficient for systems of at most 400 variables.

#### Solver for constraints expressed in Answer Set Programming (Clasp)

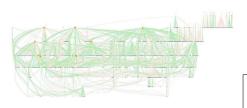
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- Provides one solution for a given set of constraints.
- Very efficient with thousands of variables.

# Question 1 : consistency

- Biological question Are the different pieces of information coherent with each other ?
- Computer scientist question Do the system of constraint admit at least a solution ?
- Solution Write an ASP program and check for the existence of a solution
- Alternative solution Check wether the system of equations has a solution with Decision Diagrams

Example : the network of transcriptional interactions for E. Coli given by Regulon DB is not internally coherent.



- Large scale network with hierarchical structure (87% of genes are regulated by 13%)
- 160 doubled signed interactions
- 1100 constaints, 1258 variables

Number of nodes	1258
Number of interactions	2526
Nodes without successor	1101
Nodes with more than 80 successors	7
protein complex	4

# Underlying modules

## Core of a system

The core of a biological system described by its interaction graph is the smallest subgraph such that the full system of constraints admits a solution iff the constraints generated by the subgraph admit a solution

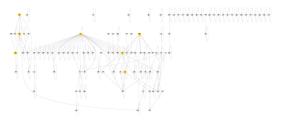
- Computation of an approximation of the graph Keep cycles of the interaction graph and their predecessors
- ▶ Used by Kauffman and Peterson to study S. Cerevisiae network.
- Concretely Recursively remove edges and nodes that do not constraint the system
- Interest The search for solutions by decision diagrams becomes possible

Morality : The core of a system contains its dynamics. The rest is static.

# Underlying modules

# Examples

 E. Coli network reduces from 1258 nodes to 105 nodes and 183 interactions. The central connected component contains only 28 nodes and 57 edges.



- E. Coli network and 43 stationnary phase experimental data reduces from 1258 to 148 nodes and 388 interactions
- S. Cervisiae assuming that the signs of interactions are known. Reduces from 2419 nodes and 4344 interactions to 31 nodes and 52 interactions
- ► S. Cervisiae with no interaction sign No reduction is possible > < = > = ∽ < @

# Question 2 : Correcting a system

- Biological question When I have contradicting data and knowledge, what should I change ?
- Origin of errors
  - Errors in experimental data or knowledge
  - Missing interaction between nodes
  - Non-constant signed action between an actor and its target
  - (Missing node)
- Computer scientist question What is the minimal set of equations that raise inconsistency?

## Underlying modules

An inconsistency module is a minimal subset of equations such that the remaining equations are consistent.

## Strategy for computation

- Decision diagrams Recursively remove systems of size 1, 2, 3..; that are internally inconsistent in order to obtain a consistency system.
- ASP Look for a minimal set of corrections to the inconsistent module. 3000

# Example : E. Coli (step 1)

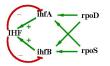


IHF	$\approx$	ihfA+ihfB	(1)
ihfA	$\approx$	-IHF	(2)
ihfB	$\approx$	-IHF	(3)

# Automatic finding of inconsistent system (no

solution)			
ihfA	ihfB	IHF	Conflict
+	+	+	(2), (3)
+	+	-	(1)
+	-	+	(1)
+	—	-	(1)
-	+	+	(1)
-	+	-	(1)
-	-	+	(1)
-	-	-	(2), (3)

Manual curated answer : Adding new interactions (sigma factors)



IHF	$\approx$	ihfA+ihfB
ihfA	$\approx$	-IHF + rpoD + rpoS
ihfB	$\approx$	-IHF + rpoD + rpoS

Protein	Gene	Function
σ <sup>70</sup>	rpoD	Transcribes most genes in growing cells
σ <sup>38</sup>	rpoS	The starvation/stationary phase sigma-factor
σ <sup>28</sup>	rpoF	The flagellar sigma-factor
$\sigma^{32}$	rpoH	The heat shock sigma-factor
σ <sup>24</sup>	rpoE	The extracytoplasmic stress sigma-factor
$\sigma^{54}$	rpoN	The nitrogen-limitation sigma-factor
σ <sup>19</sup>	fecl	The ferric citrate sigma-factor

#### Consistent system (18 solutions

among 32)

	, ,	ihfA	ihfB	IHF	
rpoD	rpoS		IIID		
+	+	+	+	+	
+	+	+	-	+	
+	+	-	+	+	
_	-	-	-	-	
-	-	-	+	-	
-	-	+	-	-	
+/-	-/+	+	+	+	
+/-	-/+	+	-	+	
+/-	-/+	+	-	-	
+/-	-/+	-	+	+	
+/-	-/+	-	+	-	
+/-	-/+	-	-	-	

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# Example : E. Coli (step 2)

## New (consistent) model and data on exponential phase

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Number of nodes	1529
Number of interactions	3883
Nodes without successor	1365
Nodes with more than 80 successors	10
sigma-factors	6
protein complex	4

gene	effect								
acnA	+	csiE	+	gadC	+	osmB	+	recF	+
acrA	+	cspD	+	hmp	+	osmE	+	rob	+
adhE	+	dnaN	+	hns	+	osmY	+	sdaA	-
appB	+	dppA	+	hyaA	+	otsA	+	sohB	-
appC	+	fic	+	ihfA	-	otsB	+	treA	+
appY	+	gabP	+	ihfB	-	polA	+	yeiL	+
blc	+	gadA	+	Irp	+	proP	+	yfiD	+
bolA	+	gadB	+	mpl	+	proX	+	yihl	-

### Model and data are inconsistent!

Correction algorithm. There was a mistake on data provided by RegulonDB Good variations : ihfA = + and ihfB = + (confirmed by the litterature)

# Example : S. Cervisiae

## Several unsigned networks for S. Cervisiae

- Core of S. Cervisiae [31 nodes, 52 edges]
- Unsigned interactions between transcription factors (from Chip-Chip analyses or promoteur inference) [70/83 nodes, 96/131 edges]
- Full interaction network given by Chip-Chip analyses (Lee et al, 2002) [2419 nodes 4344 edges]

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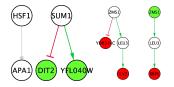
### Several datasets

- 15 quite complete stress experimental datasets (YDB)
- About 300 mutant experimentations (Hugues et al, 2000)

## All unsigned networks are inconsistent with the datasets

# Example : S. Cervisiae (correction)

## We identify inconsistent subsets for each network



Interaction network	Nodes	Edges	Number Exp.	Input/Output obs. simult.	MBM Int. Typel			M Int. II,III,IV
(A) Core of Lee network	31	52	15	46	3 (5.7%)			0
(B) Extended Lee network	70	96	15	70	7	(7.2%)		0
(C) Inferred network	83	131	14	91	4	(3%)	0	
(D) Global network	2419	4344	14	2270	281	(6.5%)	463 (11%)	

## Obtaining the largest block? To be done

# Question 3 : Predictions of a system

- Biological question What do the knowledge and data predict on nonobserved signed and/or products ?
- Computer scientist question What are the variables whose sign is the same in all solutions ?

## Associated module : hard component

The hard component of a system of constraints is the set of variables that are affected with the same sign in all the solutions to the constraints.

- Decision Diagram Explicitly study the tree of solutions (limited size of nodes)
- ► ASP For each variable, check whether the systems S and (X = +) and S and (X = -) have a solution (30 seconds for each node).

Example : E. Coli and 40 stationnary phase data Allows to infer 401 new variations (that is, 26 % of the network)

# Large scale network with large core

- Decision Diagrams cannot be used and constraint solvers are too long.
- The good strategy : decompose into submodules
  - Partition the set of equations into subsets of equations that share the minimum variables

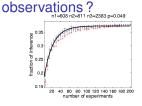
Obtained by ASP computing

- For each set of variables, use decision diagrams to eliminate variables outside the considered set
- Solve the remaining constraints.

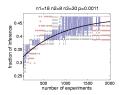
# Unsigned E. Coli graph and predictability of signs

- Large consistent graph : 1529 nodes and 3802 edges.
- Core of the graph : 28 nodes and 57 edges.
- Random production of consistent sets of signs of variations that simulate random experimental datasets

## How many signs can we predict from a given set of



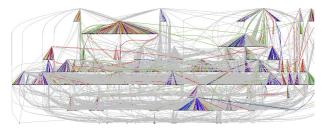
- A maximum of 40,7 % of the graph can be infered.
- In average, 30 experimental datasets are enough to infer 30% of the network.
- 600 signs can be infered from a unique suitable dataset.
- 800 signs can be infered with a probability 0.05.



- A maximum of 47,3 % of the graph can be infered.
- In average, 100 experimental datasets are enough to infer 30% of the network.
- Not all observations have equivalent impact on sign inference

# Example : S. Cervisiae

- About 15% of unsigned networks are inconsistent
- About 15% of the remaining unsigned interactions can be infered from 15 datasets.



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# Question 4 : Key nodes?

## Validation power

- Biological question What are the most important 15 nodes to be observed to ensure that my model is good ?
- Computer scientist question What si the group of 15 nodes that belongs to the minimal number of consistent solutions ?
- Computation To be done (Decision Diagram + ASP)

## Prediction power

- Biological question What are the most important 15 nodes to be observed to have the most important influence on the network?
- Computer scientist question What is the group of 15 nodes that have the most important hard component whatever the consistent signs we consider ?
- Computation To be done (Decision Diagram + ASP)

## Conclusions

- Many questions asked by biologists can be solved by using a static approach and constraints solvers
- Each question is associated with a class of modules that can often be computed
- Some of these modules are intrinsicly dynamical and other are static
- More than the size of the network, the important thing is the size of the reduced module associated to a question.

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